

# Chaotic Optimization for Quadratic Assignment Problems

Tohru Ikeguchi<sup>1</sup>, Keiichi Sato<sup>1</sup>,  
Mikio Hasegawa<sup>2</sup>, and Kazuyuki Aihara<sup>3</sup>

[tohru@ics.saitama-u.ac.jp](mailto:tohru@ics.saitama-u.ac.jp).

<sup>1</sup> Saitama University,

<sup>2</sup> Communication Research Laboratory,

<sup>3</sup> The University of Tokyo

# Introduction

Combinatorial Optimization Problems

Scheduling, Vehicle routing, Assignment problems, etc . . .



Almost impossible to obtain optimal solutions



Develop effective algorithms, which offer very good  
near optimum solutions in a reasonable time.

# Quadratic Assignment Problem

One of the most difficult NP-hard combinatorial optimization problems.

$$F(\mathbf{p}) = \sum_{i=1}^N \sum_{j=1}^N c_{ij} d_{p(i)p(j)}$$

$c_{ij}$  : the  $(i, j)$  th element of a flow matrix  $\mathbf{C}$

$d_{ij}$  : the  $(i, j)$  th element of a distance matrix  $\mathbf{D}$

$p_i$  : the  $i$  th element of a permutation  $\mathbf{p}$

$N$  : the size of the problem

Find a permutation  $\mathbf{p}$ , which provides the minimum value of the objective function  $F$ .

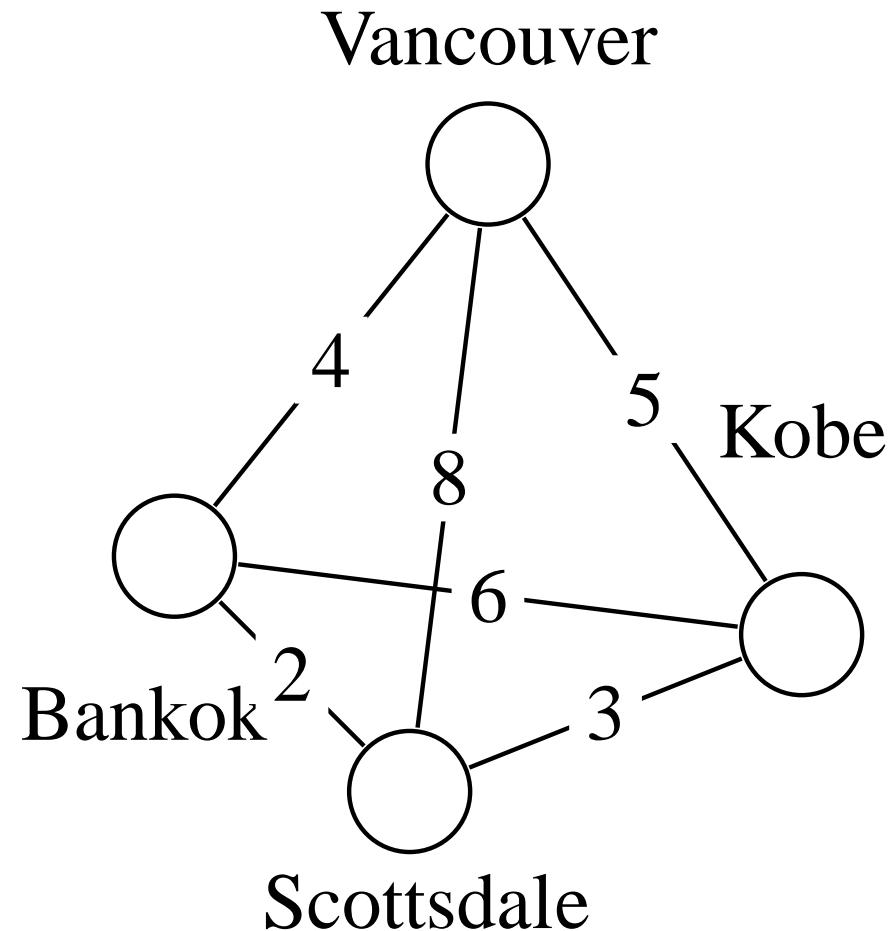
# Example of QAP

1. Assign 4 factories, X, Y, Z and W, to the four cities
2. The amounts of items between 4 factories

$$C = \begin{matrix} & X & Y & Z & W \\ X & \left( \begin{matrix} 0 & 4 & 3 & 5 \\ 4 & 0 & 6 & 3 \\ 3 & 6 & 0 & 4 \\ 5 & 3 & 4 & 0 \end{matrix} \right) \\ Y \\ Z \\ W \end{matrix}$$

3. Distance

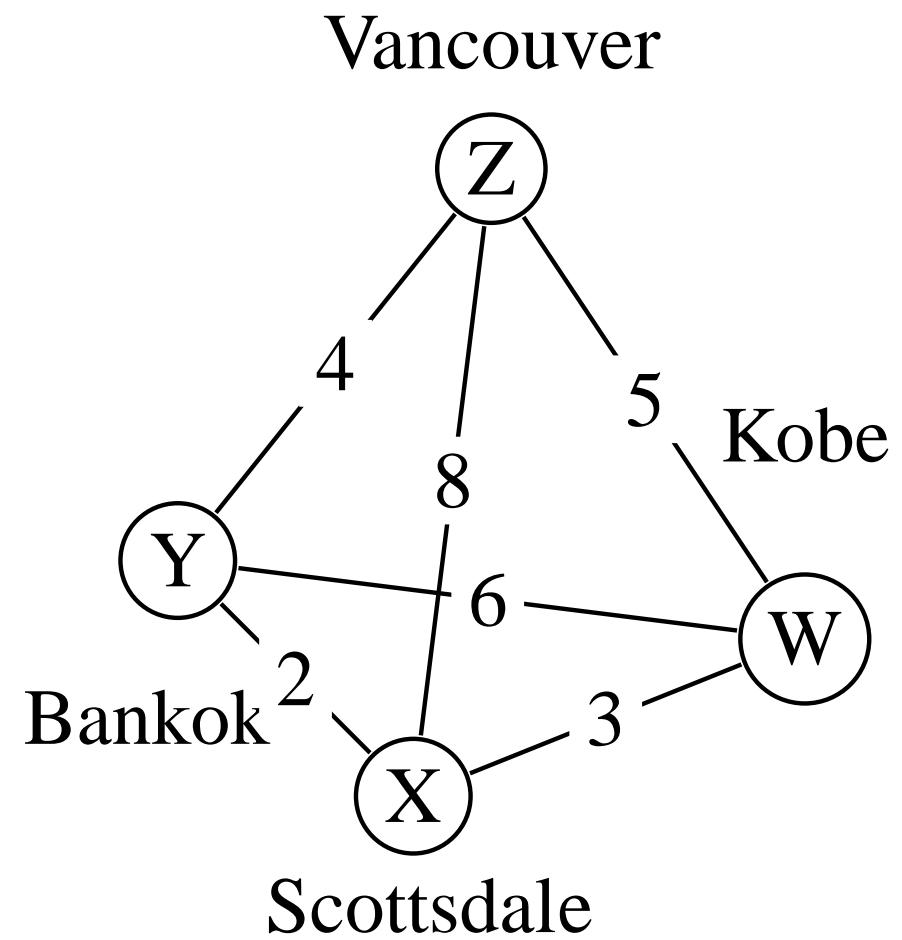
$$D = \begin{matrix} & S & B & V & K \\ S & \left( \begin{matrix} 0 & 2 & 8 & 3 \\ 2 & 0 & 4 & 6 \\ 8 & 4 & 0 & 5 \\ 3 & 6 & 5 & 0 \end{matrix} \right) \\ B \\ V \\ K \end{matrix}$$



# Example of QAP

Assignment

X	Scottsdale
Y	Bangkok
Z	Vancouver
W	Kobe



$$F(p_1) = 4 \cdot 2 + 3 \cdot 8 + 5 \cdot 3 + 4 \cdot 6 + 3 \cdot 6 + 4 \cdot 5 = 109$$

# Example of QAP

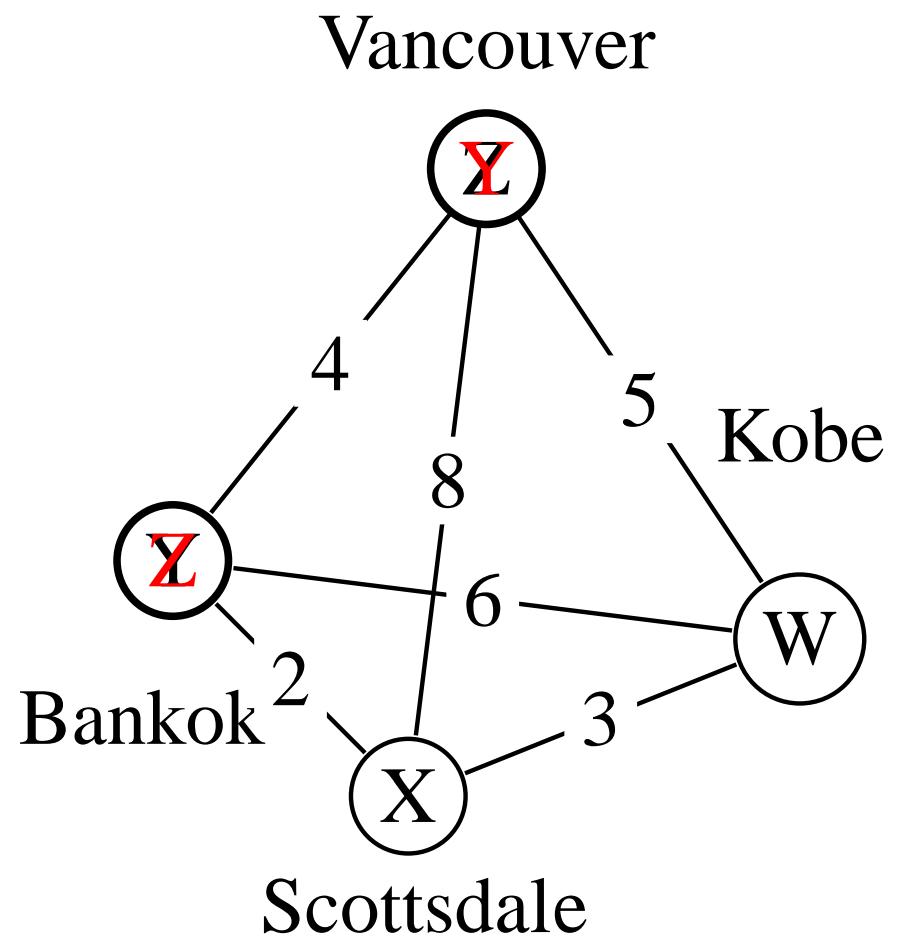
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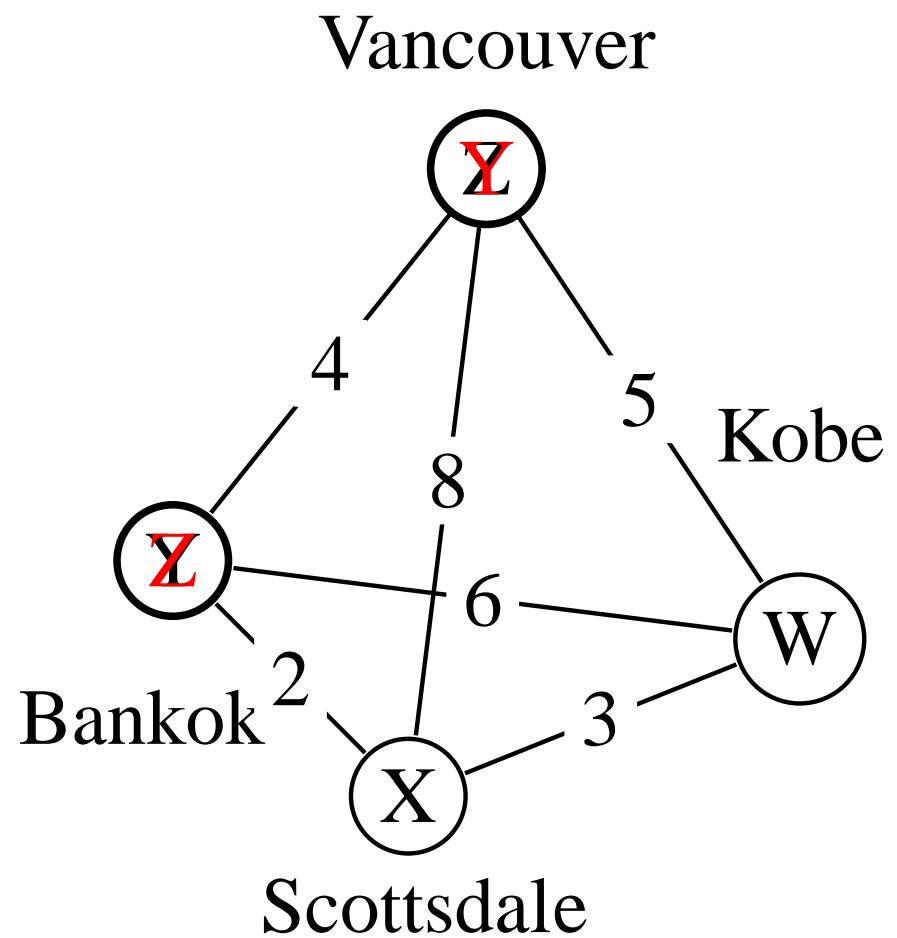
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$$F(p_1) < F(p_2)$$

# One of the conventional method

Approach based on the gradient dynamics of  
mutual connection neural networks  
(Hopfield – Tank neural network approach)

- Good news  
We can obtain good solutions (possibly optimum) if we can decide connection weights with appropriate initial conditions.

# Coding

- Solving an  $N$ -size problem,  $N \times N$  neurons are prepared.
- The  $(i, m)$ -th neuron firing ( $x_{im} = 1$ ) assigns the  $i$ -th element to the  $j$ -th element.

	S	B	V	K
X	○	○	○	○
Y	○	○	○	○
Z	○	○	○	○
W	○	○	○	○

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	S	B	V	K
X	1	0	0	0
Y	0	1	0	0
Z	0	0	1	0
W	0	0	0	1

1 → Firing, 0 → Resting.

X : Scottsdale, Y : Bangkok, Z : Vancouver and W : Kobe.

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X : Vancouver, Y : Bangkok, Z : Kobe and W : Scottsdale.

# Connection Weights

$$F(x) = A \sum_{i=1}^N \left( \sum_{m=1}^N x_{im} - 1 \right)^2 + B \sum_{m=1}^N \left( \sum_{i=1}^N x_{im} - 1 \right)^2 \\ + \sum_{i=1}^N \sum_{m=1}^N \sum_{j=1}^N \sum_{n=1}^N c_{ij} d_{mn} x_{im} x_{jn},$$

$$E(x) = -\frac{1}{2} \sum_{i=1}^N \sum_{m=1}^N \sum_{j=1}^N \sum_{n=1}^N w_{im;jn} x_{im} x_{jn} + \sum_{i=1}^N \sum_{m=1}^N \theta_{im} x_{im}$$

$$w_{im;jn} = -2\{A(1 - \delta_{mn})\delta_{ij} + B\delta_{mn}(1 - \delta_{ij}) + c_{ij}d_{mn}\}$$

A, B : positive constants,  $\delta_{ij}$  : Kronecker's delta

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(Hopfield – Tank neural network approach)

- Good news  
We can obtain good solutions (possibly optimum) if we can decide connection weights with appropriate initial conditions.
- Bad news
  1. Difficult to apply to large scale size problems  
 $N$ -size problem  $\rightarrow N^2$  neurons  $\rightarrow N^4$  connections
  2. Unfeasible solutions
  3. Local minimum problem

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- Chaotic dynamics for escaping from local minima.

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Mutual connection NN → CNN for TSPs

Nozawa, 1992

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- CNN for QAPs

# Chaotic neural network

$$y_{im}(t + 1) = k y_{im}(t) + \sum_{j=1}^N \sum_{n=1}^N w_{im;jn} x_{jn}(t) - \alpha f(y_{im}(t)) + a_{im}$$

$y_{im}(t)$  : the internal state of the  $(i, m)$  th neuron at  $t$

$w_{im;jn}$  : the connection weight

$f$  : output function,  $f(z) = 1/(1 + \exp(-z/\epsilon))$

$k$  : the decay parameters for the refractoriness

$\alpha, a, \epsilon$  : parameters

# Use CNN to solve QAPs

$$\begin{aligned} F(x) = & A \sum_{i=1}^N \left( \sum_{m=1}^N x_{im} - 1 \right)^2 + B \sum_{m=1}^N \left( \sum_{i=1}^N x_{im} - 1 \right)^2 \\ & + \sum_{i=1}^N \sum_{m=1}^N \sum_{j=1}^N \sum_{n=1}^N c_{ij} d_{mn} x_{im} x_{jn}, \end{aligned}$$

$$w_{im;jn} = -2\{A(1 - \delta_{mn})\delta_{ij} + B\delta_{mn}(1 - \delta_{ij}) + \frac{c_{ij}d_{mn}}{q}\}$$

$q$  : a normalization parameter

# Definition of firing

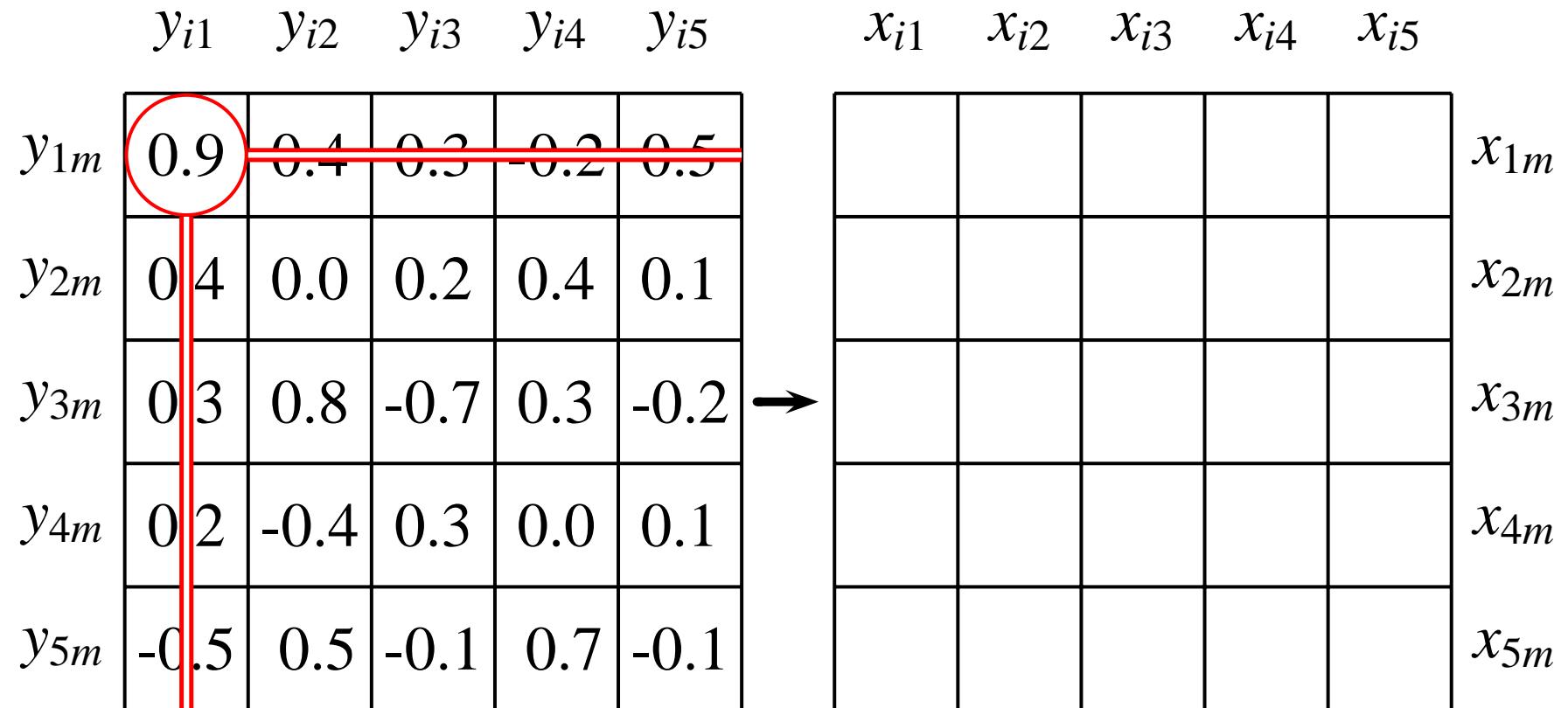
	$y_{i1}$	$y_{i2}$	$y_{i3}$	$y_{i4}$	$y_{i5}$		$x_{i1}$	$x_{i2}$	$x_{i3}$	$x_{i4}$	$x_{i5}$		$x_{1m}$	
$y_{1m}$	0.9	0.4	0.3	-0.2	0.5									$x_{1m}$
$y_{2m}$	0.4	0.0	0.2	0.4	0.1									$x_{2m}$
$y_{3m}$	0.3	0.8	-0.7	0.3	-0.2									$x_{3m}$
$y_{4m}$	0.2	-0.4	0.3	0.0	0.1									$x_{4m}$
$y_{5m}$	-0.5	0.5	-0.1	0.7	-0.1									$x_{5m}$

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$y_{5m}$	-0.5	0.5	-0.1	0.7	-0.1							$x_{5m}$

→

# Definition of firing



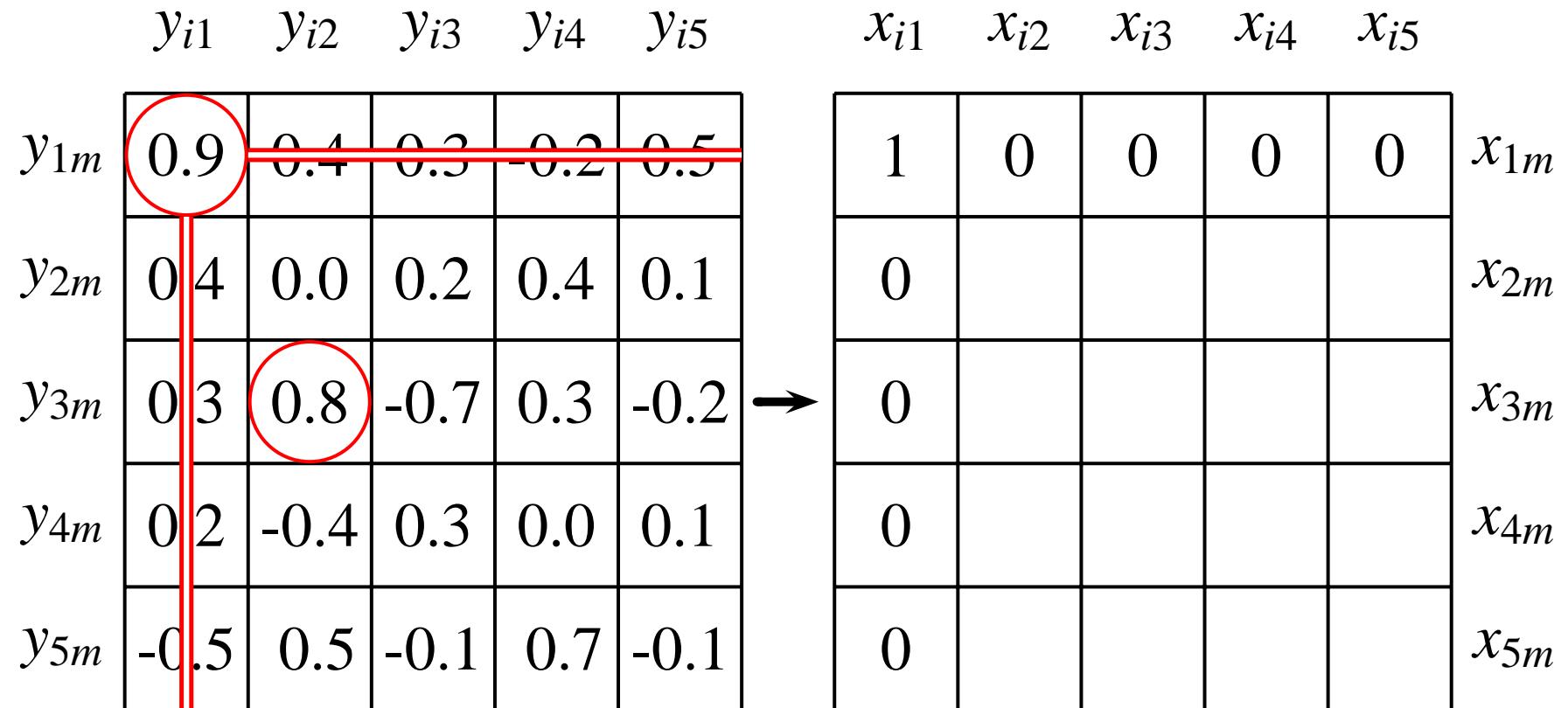
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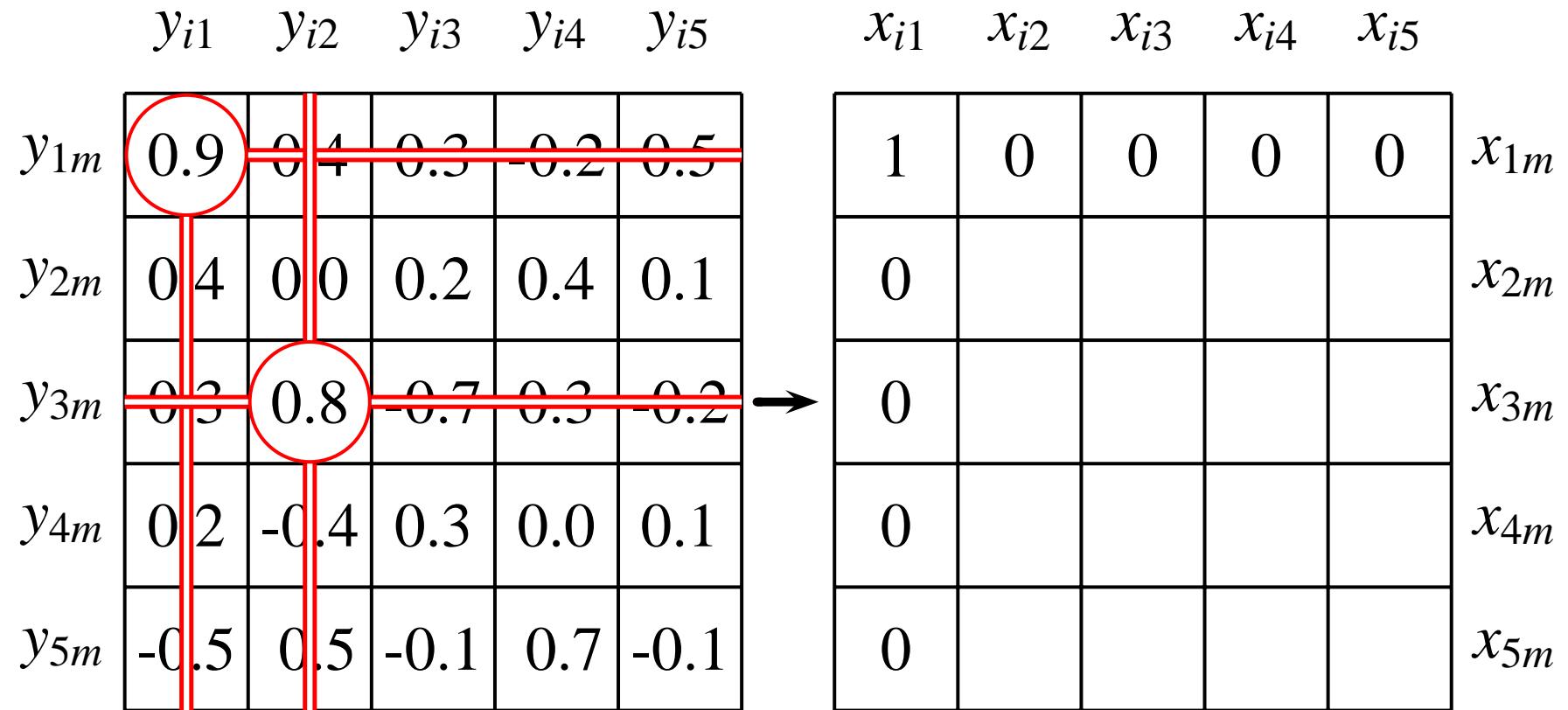
→

	$x_{i1}$	$x_{i2}$	$x_{i3}$	$x_{i4}$	$x_{i5}$	
$x_{1m}$	1	0	0	0	0	
$x_{2m}$	0					
$x_{3m}$	0					
$x_{4m}$	0					
$x_{5m}$	0					

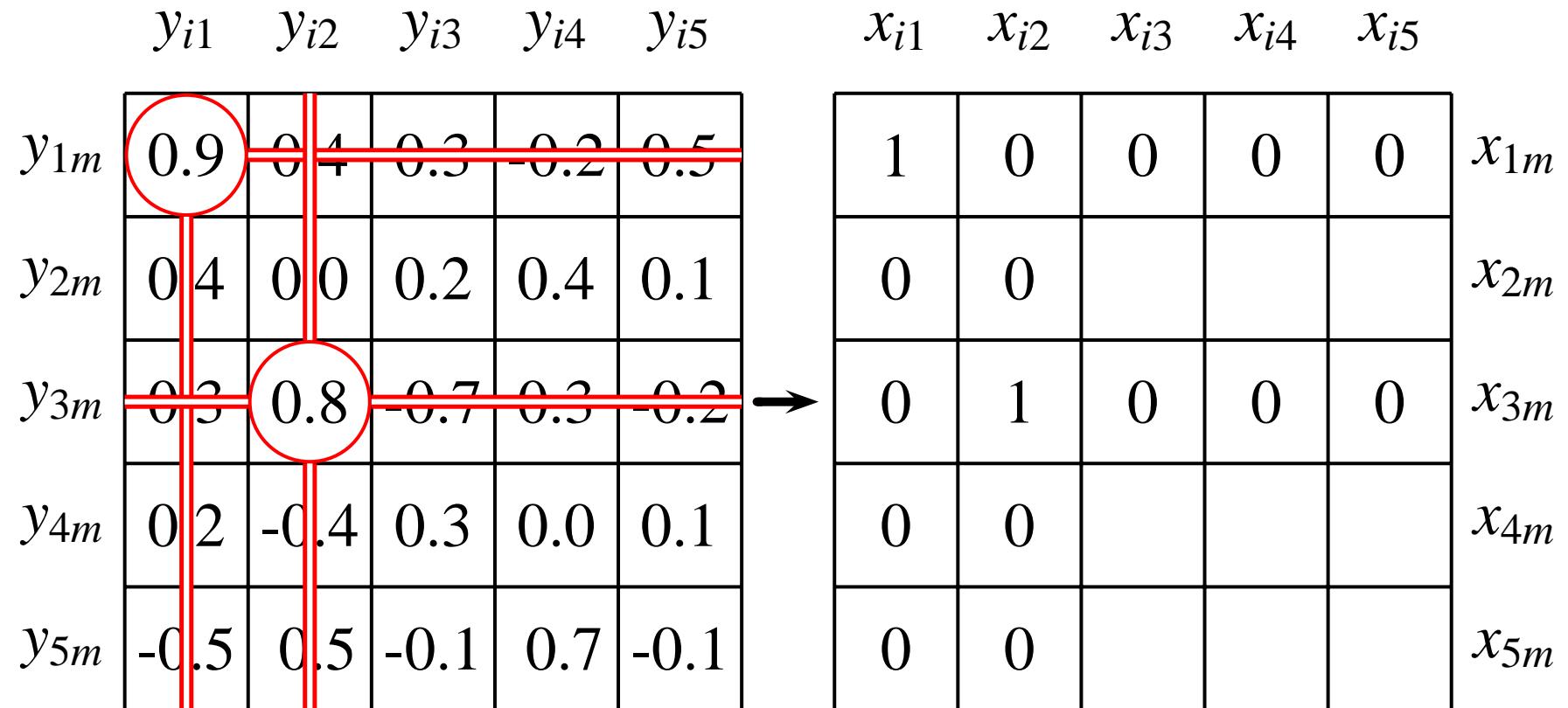
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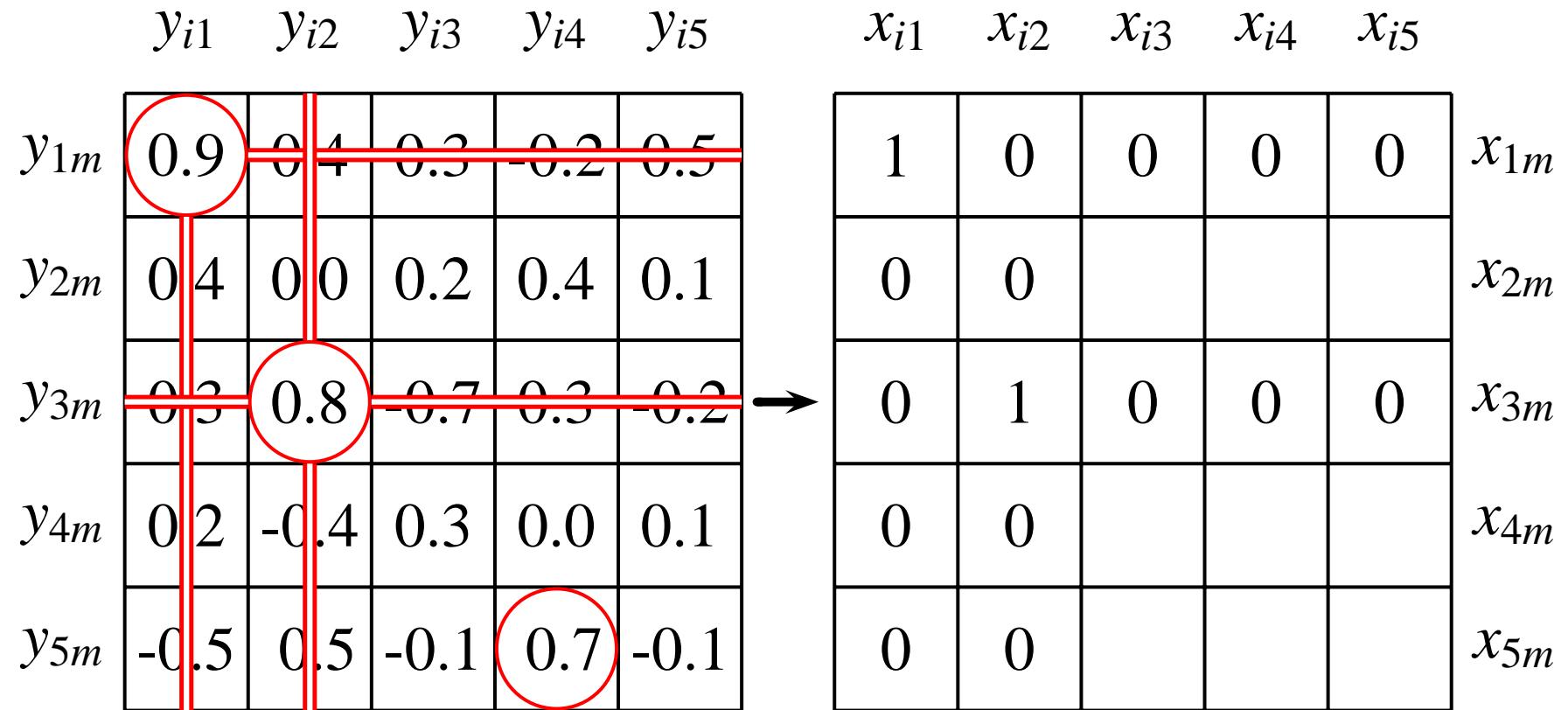
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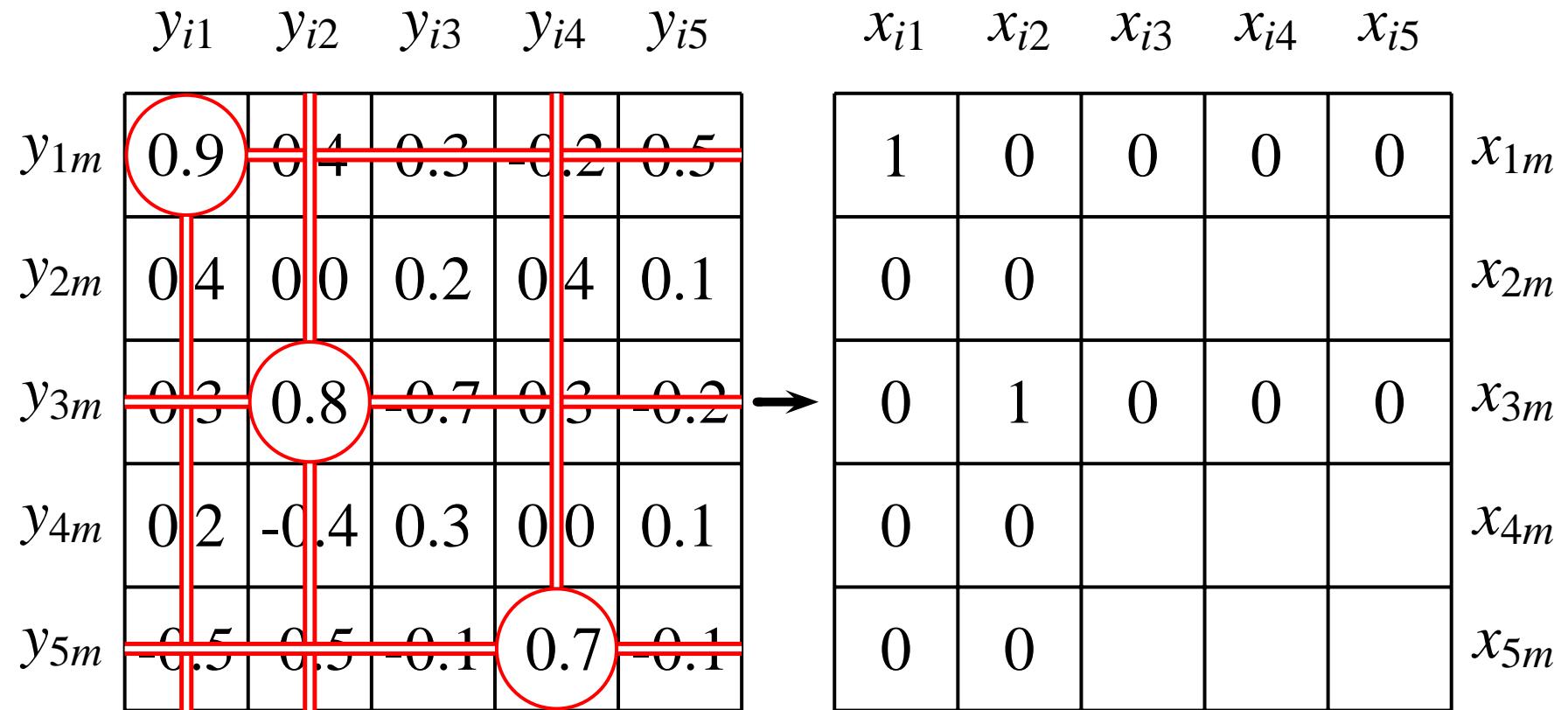
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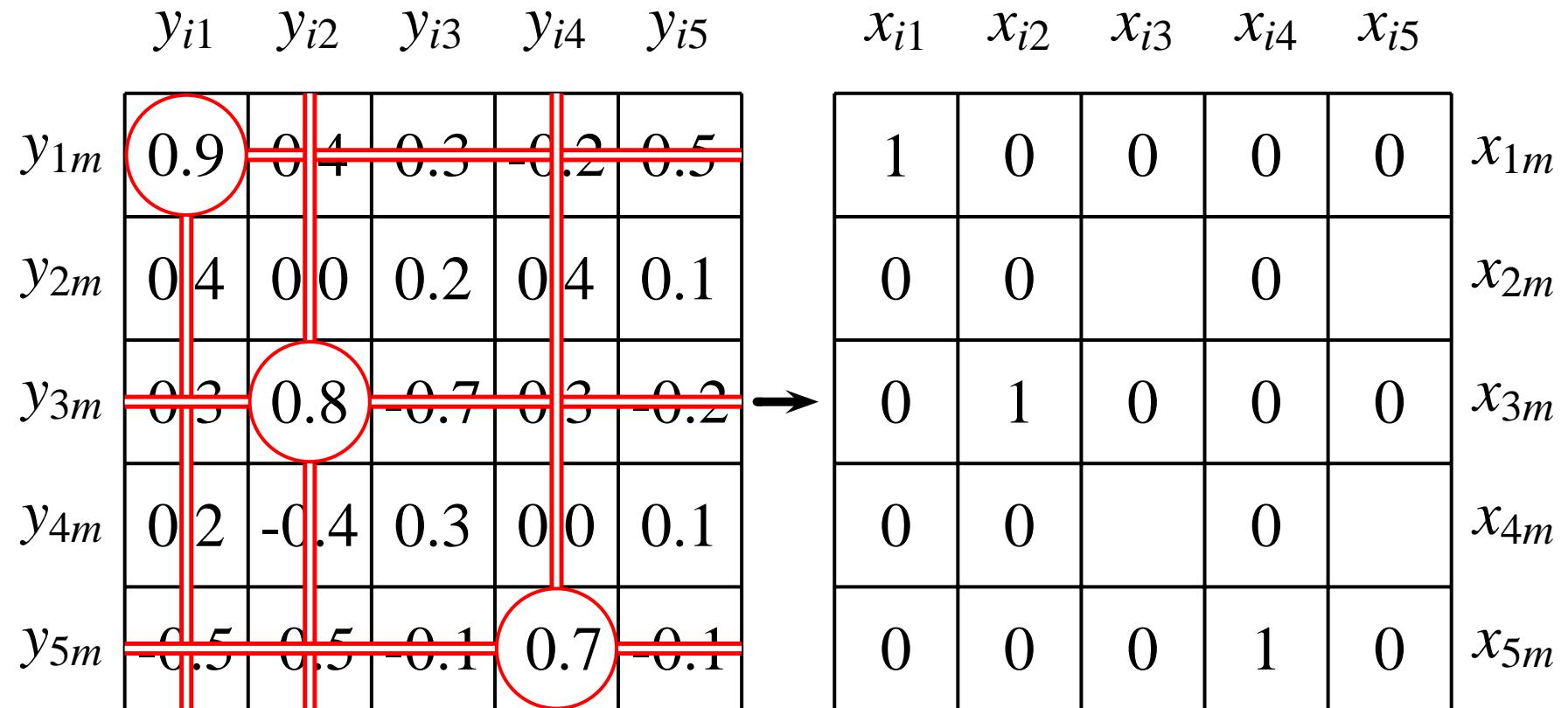
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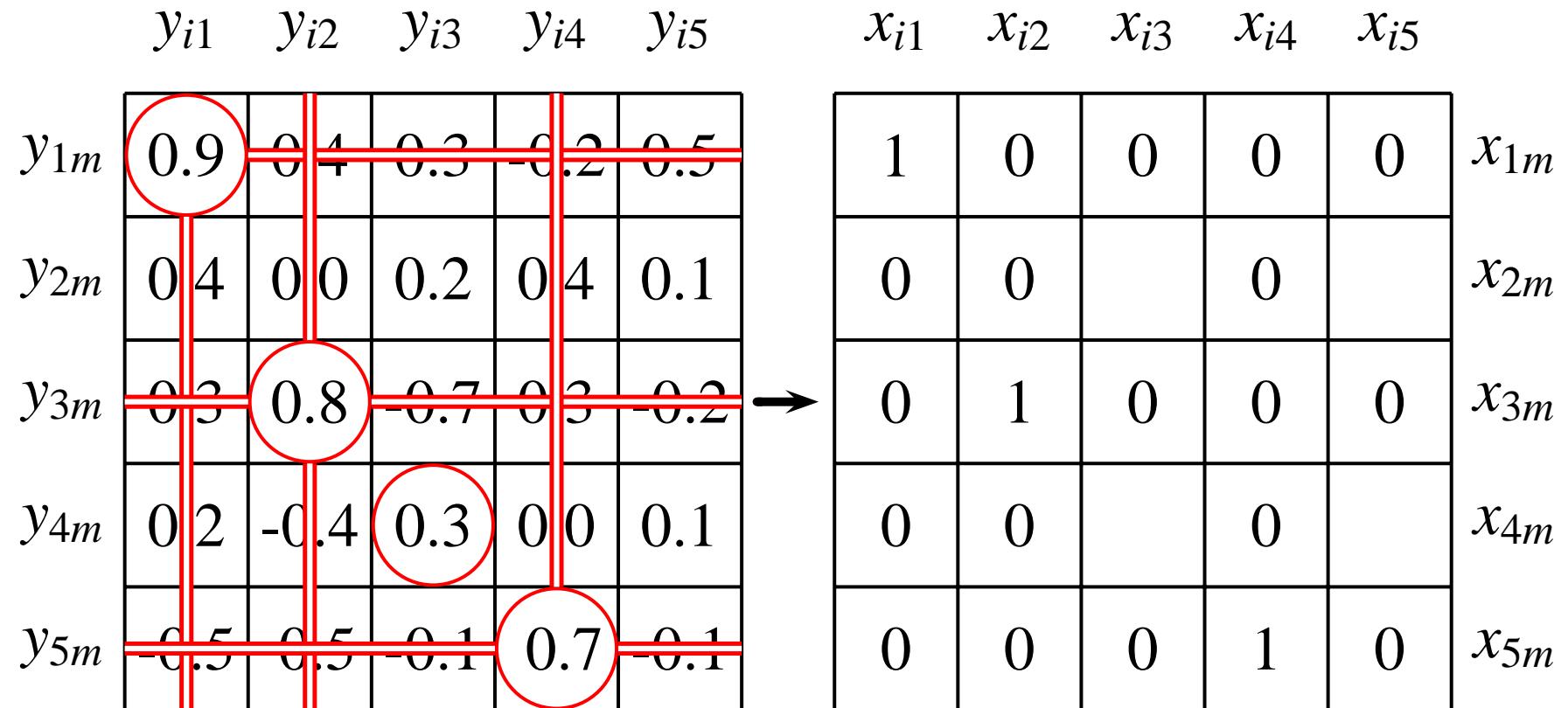
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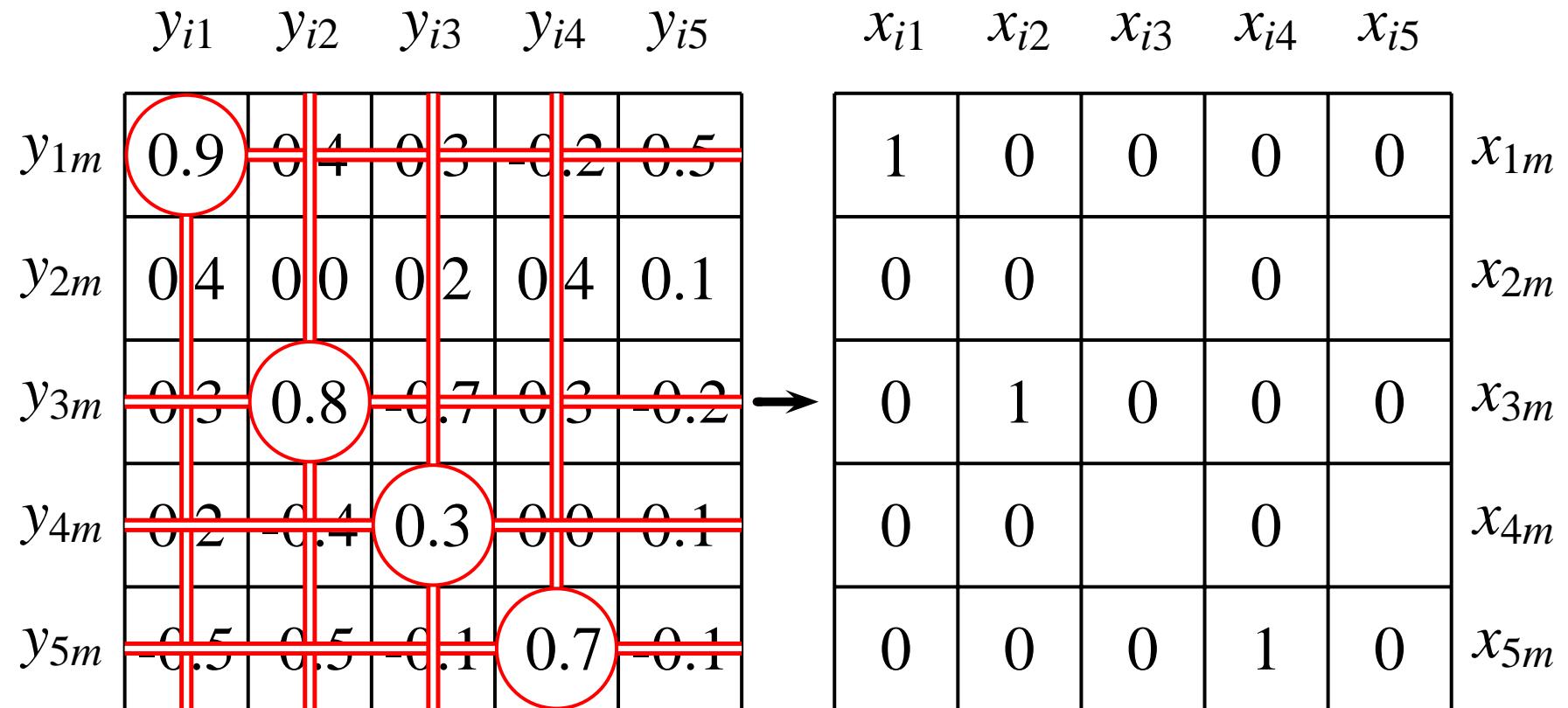
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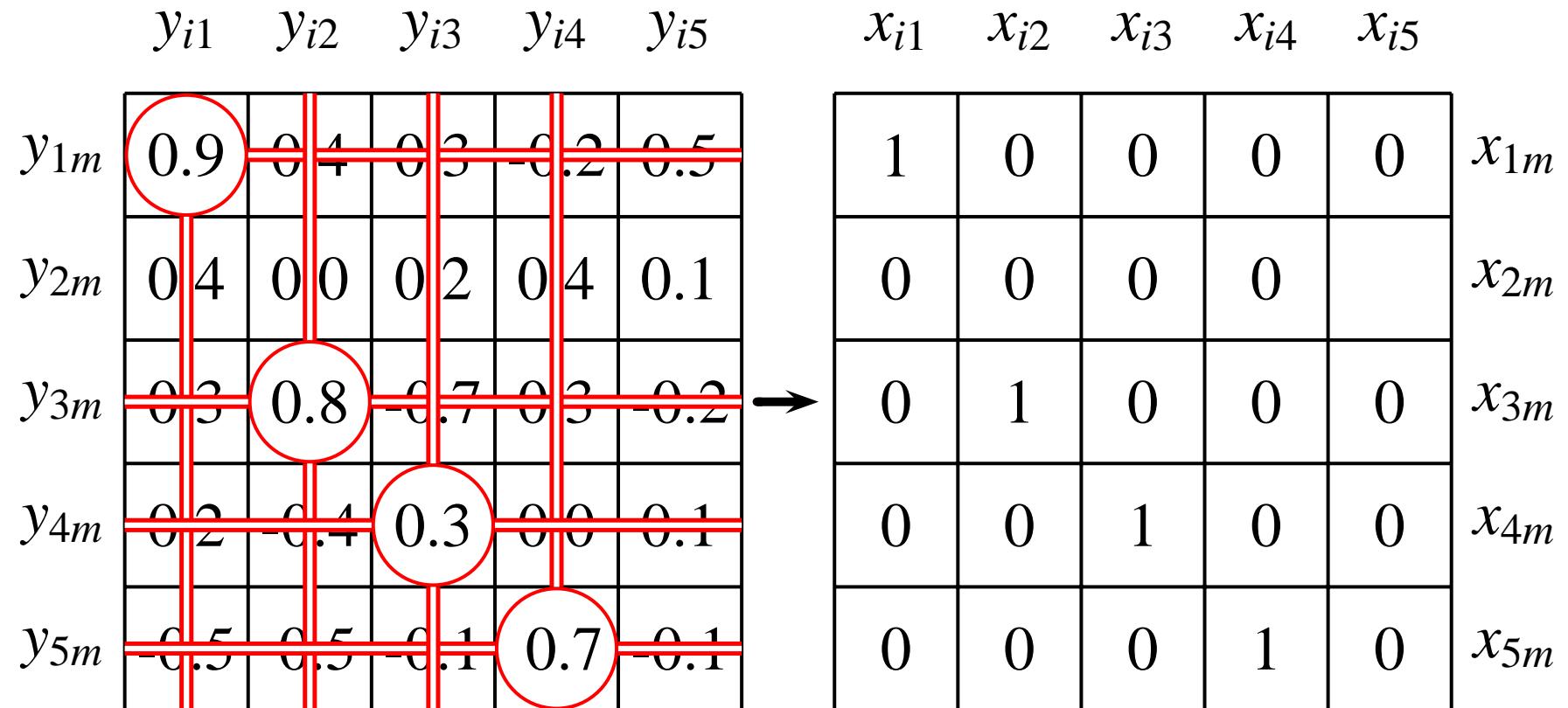
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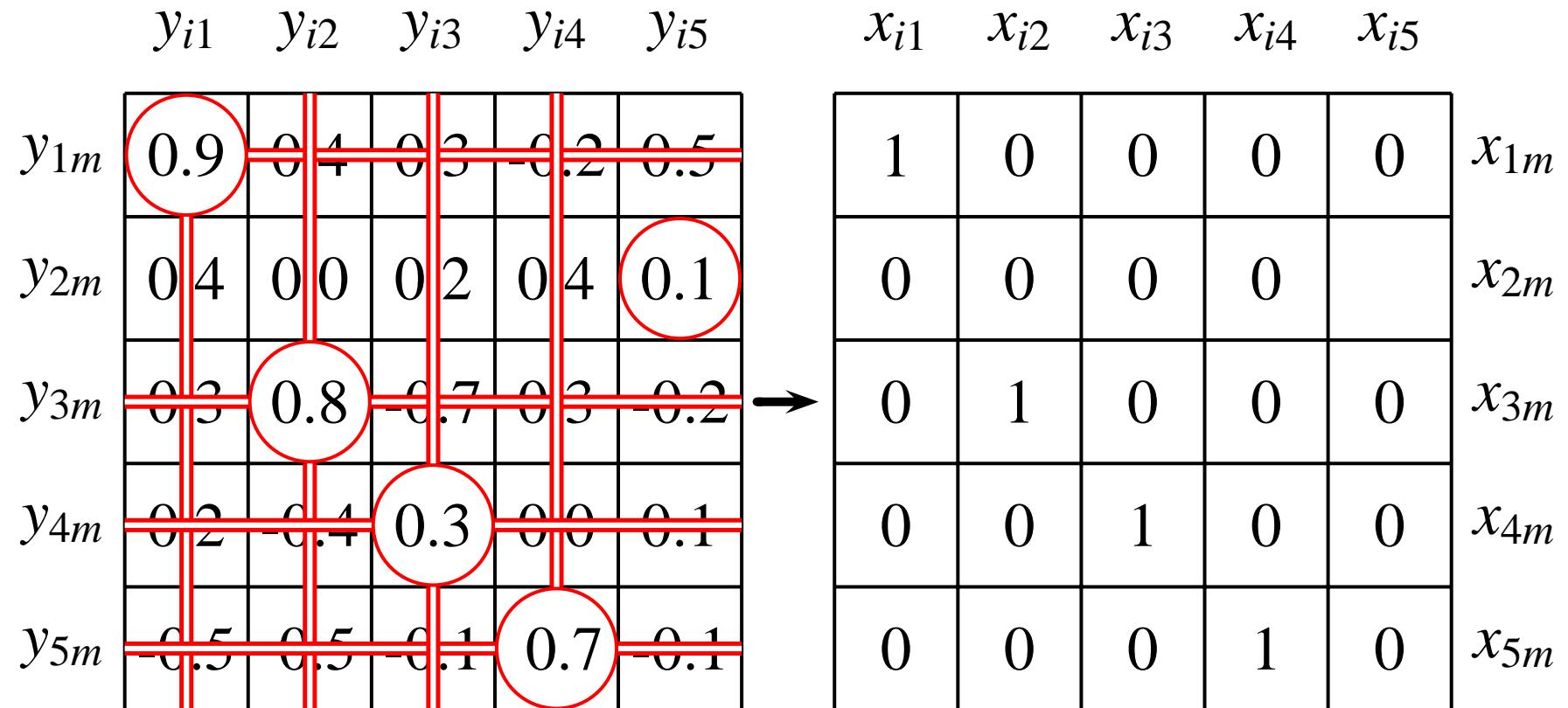
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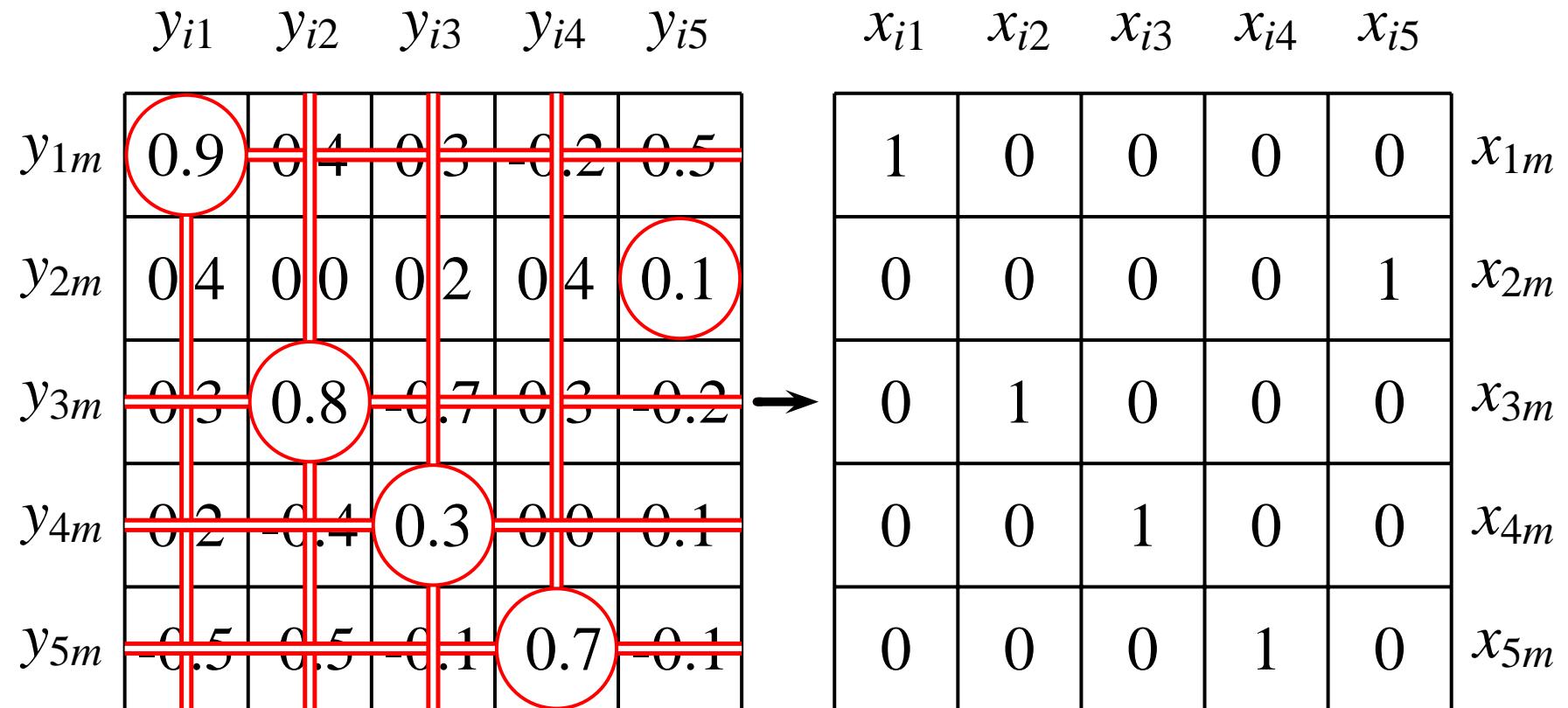
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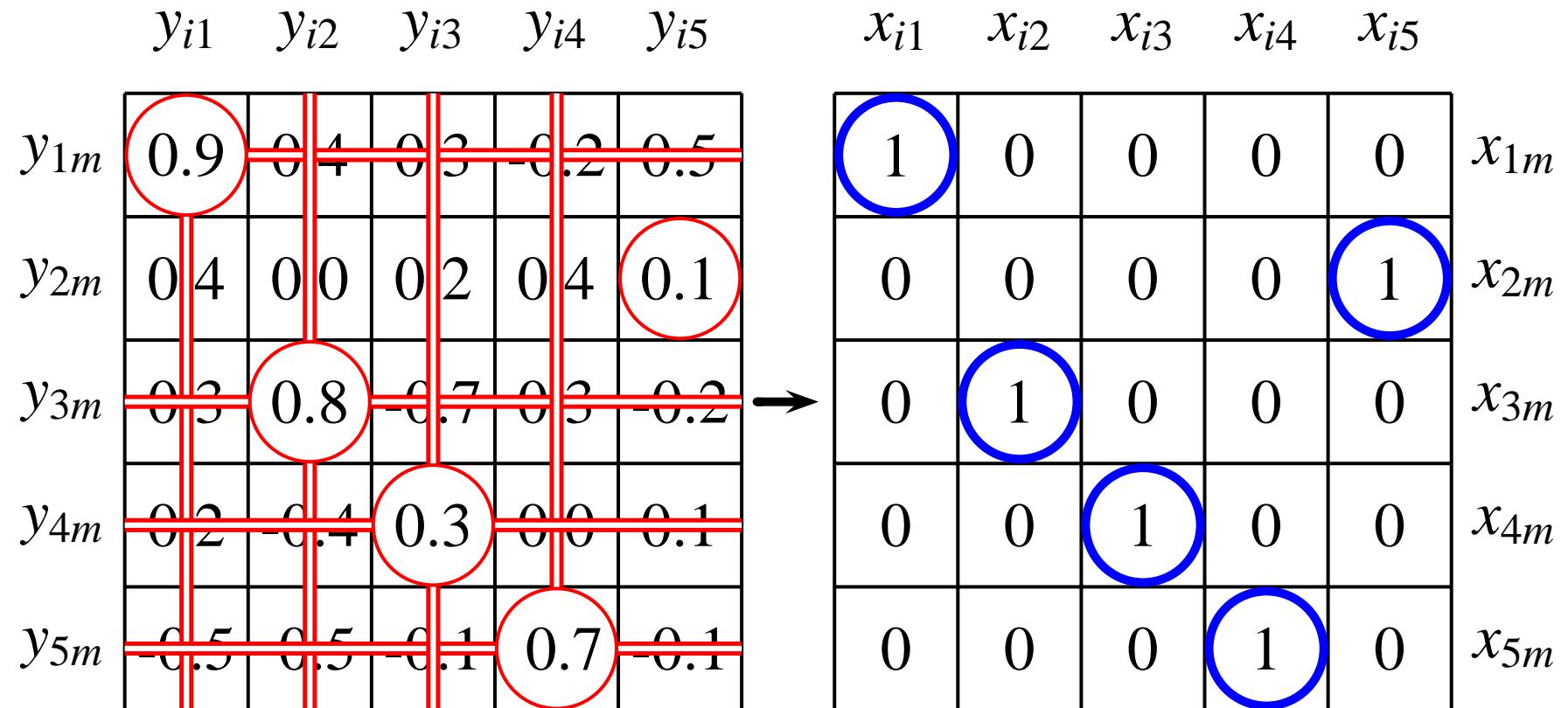
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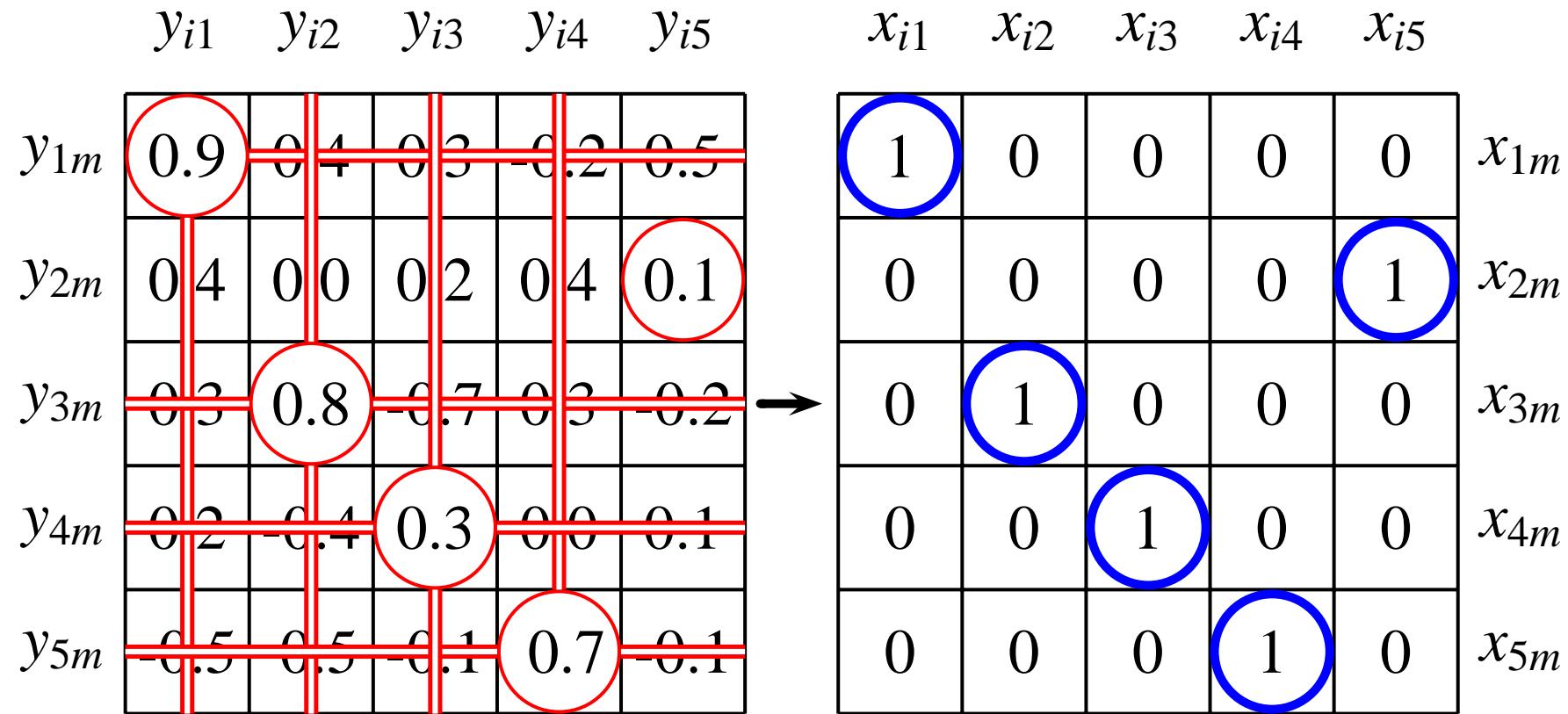
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This coding scheme always offers feasible solutions.



Higher solvable performance

# Benchmark problems

- From QAPLIB  
(URL: <http://www.opt.math.tu-graz.ac.at/qaplib/>)

1. Nug

$$N = 12, 14, 15, 16, 17, 20, 21, 22, 24, 25, 27, 30$$

2. Had

$$N = 12, 14, 16, 18, 20$$

# Chaotic Dynamics and Solvable Performance

We evaluate the solvable performance on benchmark problems by calculating

1. Lyapunov dimension
  2. sum of positive Lyapunov exponents
  3. the number of positive Lyapunov exponents
- for 1,000 parameter sets  $(a, k)$ .

$$3 \leq a \leq 8, 0.8 \leq k < 1$$

$$A = B = 0.5, \alpha = 1.01, \epsilon = 0.02,$$

# Estimating Lyapunov Exponents

$$\begin{aligned} \mathbf{y}(t+1) &= F(\mathbf{y}(t)) \\ \mathbf{y}(t+1) + \Delta\mathbf{y}(t+1) &= F(\mathbf{y}(t) + \Delta\mathbf{y}(t)) \\ \Delta\mathbf{y}(t+1) &= DF(\mathbf{y}(t))\Delta\mathbf{y}(t) \end{aligned}$$

$DF(\mathbf{y}(t))$  : Jacobian matrix at  $\mathbf{y}(t)$

$$\mathbf{y}(t) = \begin{pmatrix} y_{11}(t) \\ y_{12}(t) \\ y_{13}(t) \\ \dots \\ y_{NN}(t) \end{pmatrix} \in \mathbf{R}^{N^2}$$

# QR decomposition

$$DF(y(0)) = Q_1 R_1$$

$$DF(y(1))Q_1 = Q_2 R_2$$

$$DF(y(2))Q_2 = Q_3 R_3$$

...

$$DF(y(t))Q_t = Q_{t+1} R_{t+1}$$

...

$$\lambda_i = \lim_{n \rightarrow \infty} \frac{1}{n} \sum_{t=1}^n \log |R_t^{ii}|$$

where  $R_t^{ii}$  is the  $i$ -th diagonal element of  $R_t$ .

# Lyapunov dimension

- Lyapunov dimension

$$D_L = j + \frac{\sum_{i=1}^j \lambda_i}{\lambda_{j+1}}, \quad j = \max_k \left\{ \sum_{i=1}^k \lambda_i > 0 \right\}$$

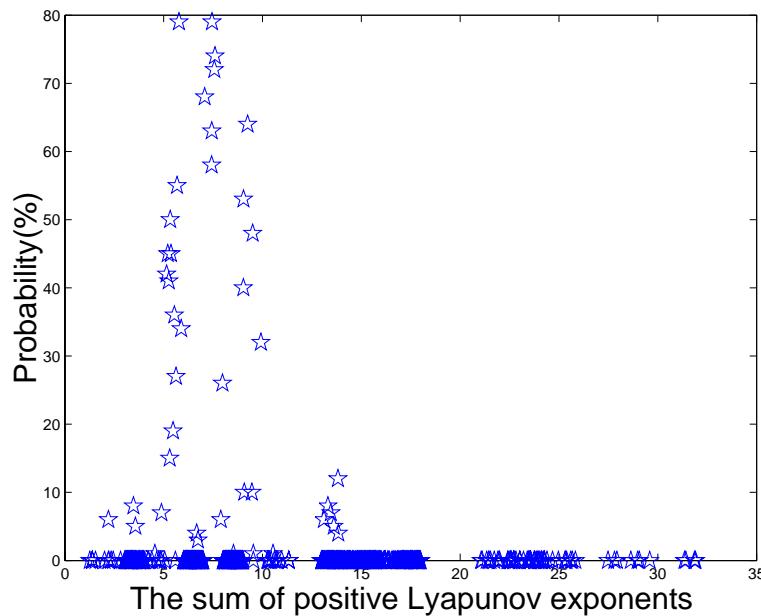
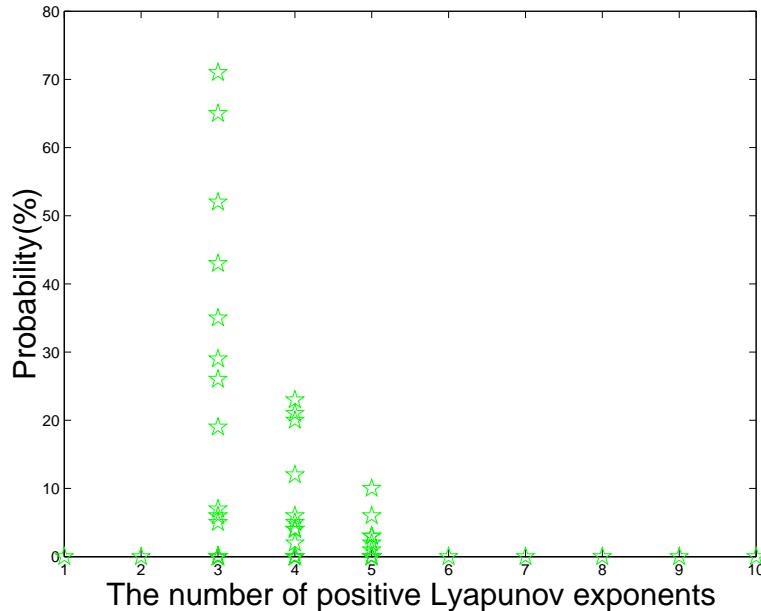
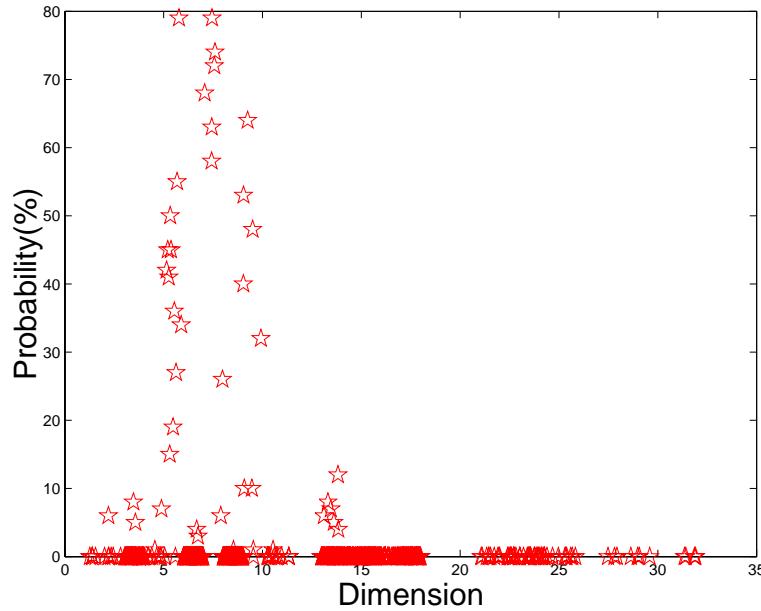
- # of positive Lyapunov exponents  $p$

$$\lambda_1 > \lambda_2 > \cdots \lambda_p > 0 > \lambda_{p+1} > \cdots \lambda_{N^2}$$

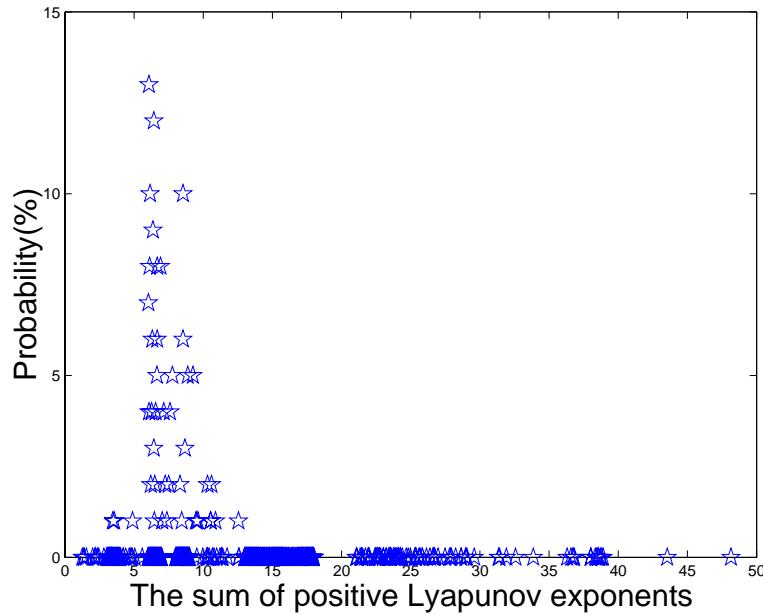
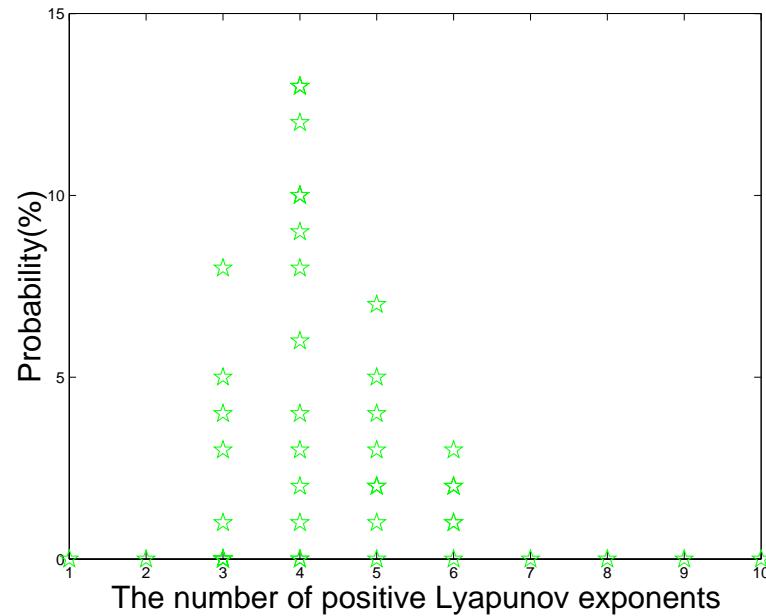
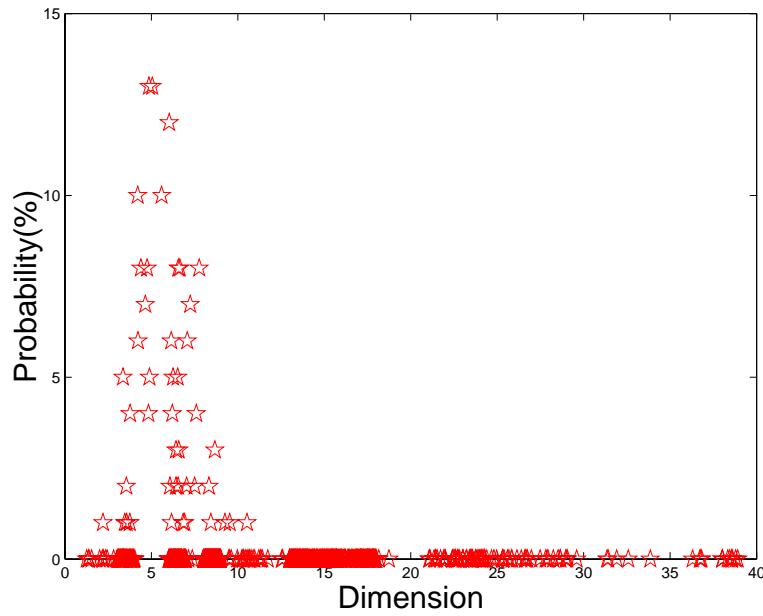
- Sum of positive Lyapunov exponents  $S$

$$S = \sum_{i=1}^p \lambda_i$$

# Results for Nug12 (578)



# Results for Nug16 (1240)



# How to find a good parameter set?

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1. Robust application for

different type problems

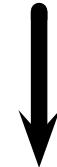
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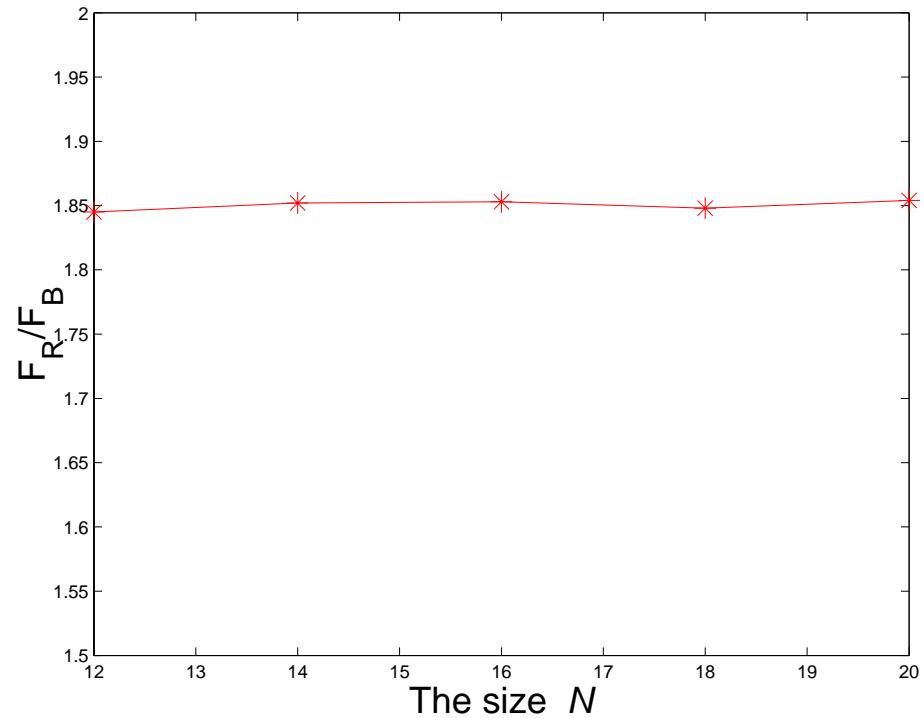
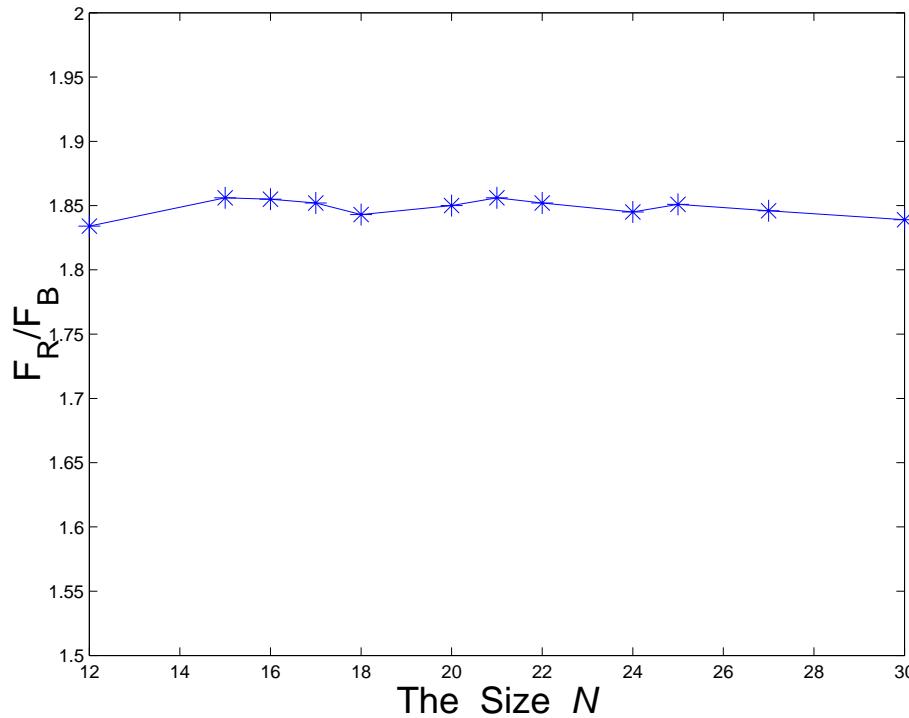
larger size problems



2 Firing rates  $F_R$  of CNN that solves an N-size problem

- $F_B = \frac{1}{N} = \frac{N}{N^2}$
- the relation between  $N$  and  $\frac{F_R}{F_B}$

# $N$ vs $F_R/F_B$



Good solutions are obtained when  $F_R \approx 1.85F_B$



Possibility to set good parameter values of CNN by observing firing rates

# Conclusions

CNN is applied for solving QAPs.

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$$\text{high performance} \iff \begin{cases} D_L & \text{small} \\ p = \sum \lambda_i, \lambda_i > 0 & \text{small} \\ S = \sum_{i=1}^p \lambda_i & \text{small} \end{cases}$$

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→ “Shy” search  $\Leftrightarrow$  CNN for Associative memories

2. How to set parameters of CNN for robust applications?
  - (a) Observe the firing rate  $F_R$
  - (b) Set parameters at  $F_R \approx 1.85/N$